ME340B - Elasticity of Microscopic Structures - Wei Cai - Stanford University - Winter 2004

Problem Set 1 Solution Index Notation and Gauss's Theorem

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Problem 1.1 (10') Index notation.

(a) Show that $\epsilon_{mkq}\epsilon_{nkq}=2\delta_{mn}$.

$$\epsilon_{mkq}\epsilon_{nkq} = \delta_{mn}\delta_{kk} - \delta_{mk}\delta_{nk}
= 3\delta_{mn} - \delta_{mn}
= 2\delta_{mn}$$

(b) Consider a rank-two tensor $p_{ij} = a\delta_{ij} + bz_iz_j$, where **z** is a unit vector $(z_iz_i = 1)$. Find the inverse q_{ij} of p_{ij} , which is defined through $q_{ij}p_{jk} = \delta_{ik}$. [Hint: suppose q_{ij} also has the form of $q_{ij} = c\delta_{ij} + dz_iz_j$.]

$$q_{ij}p_{jk} = (c\delta_{ij} + dz_iz_j)(a\delta_{jk} + bz_jz_k)$$

$$= ac\delta_{ik} + adz_iz_k + cbz_iz_k + bdz_iz_jz_jz_k$$

$$= ac\delta_{ik} + (ad + cb + bd)z_iz_k = \delta_{ik}$$

For this is to be true we require ac = 1, which implies $c = \frac{1}{a}$, and ad + cb + bd = 0. Thus

$$(a+b)d = -cb$$

$$d = -\frac{cb}{a+b}$$

$$d = -\frac{b}{a^2 + ab}$$

Thus

$$q_{ij} = \frac{1}{a}\delta_{ij} - \frac{b}{a^2 + ab}z_i z_j$$

Problem 1.2 (10') Tensor symmetry.

(a) Show that if A_{ij} is a symmetric tensor, and B_{ij} is an arbitrary tensor, then,

$$A_{ij}B_{ij} = A_{ij}B_{(ij)} (1)$$

If A_{ij} is symmetric, then $A_{ij} = A_{ji}$ and

$$(A_{ij} - A_{ji}) B_{ij} = 0$$

$$A_{ij} B_{ij} - A_{ji} B_{ij} = 0$$

$$A_{ij} B_{ij} - A_{ij} B_{ji} = 0$$

$$A_{ij} (B_{ij} - B_{ji}) = 0$$

$$A_{ij} B_{[ij]} = 0$$

Now, B can be decomposed into its symmetric and antisymmetric parts

$$A_{ij}\left(B_{(ij)} + B_{[ij]}\right) = A_{ij}B_{(ij)}$$

(b) Show that if A_{ij} is an antisymmetric tensor, then

$$A_{ij}a_ia_j=0$$

If A_{ij} is antisymmetric then $A_{ij} = -A_{ji}$ and

$$A_{ij} + A_{ji} = 0$$

$$(A_{ij} + A_{ji}) a_i a_j = 0$$

$$A_{ij} a_i a_j + A_{ji} a_i a_j = 0$$

$$2A_{ij} a_i a_j = 0$$

$$A_{ij} a_i a_j = 0$$

Problem 1.3 (10') Gauss's Theorem.

(a) For a elastic body V with surface S in equilibrium under surface traction T_i and zero body force $(b_i = 0)$, show that

$$\int_{S} T_{i} u_{i} dS = \int_{V} \sigma_{ij} e_{ij} dV$$

where u_i , σ_{ij} , e_{ij} are displacement, stress and strain fields. [Hint: Use the result in Problem 1.2.]

Start with

$$\int_{S} T_{i} u_{i} dS = \int_{S} \sigma_{ij} u_{j} n_{i} dS$$

$$= \int_{V} [\sigma_{ij} u_{j}]_{,i} dV$$

$$= \int_{V} [\sigma_{ij,i} u_{j} + \sigma_{ij} u_{j,i}] dV$$

$$= \int_{V} \sigma_{ij} u_{j,i} dV$$

$$= \int_{V} \sigma_{ij} e_{ij} dV$$

(b) Show that the average stress in the elastic body under zero body force is,

$$\overline{\sigma}_{ij} = \frac{1}{2V} \int_{S} (T_i x_j + T_j x_i) dS$$

$$\int_{S} T_{i} x_{j} dS = \int_{S} \sigma_{ik} x_{j} n_{k} dS$$

$$= \int_{V} [\sigma_{ik} x_{j}]_{,k} dV$$

$$= \int_{V} [\sigma_{ik,k} x_{j} + \sigma_{ik} x_{j,k}] dV$$

$$= \int_{V} \sigma_{ij} dV$$

similarly

$$\int_{S} T_{j} x_{i} dS = \int_{V} \sigma_{ji} dV$$

Which gives

$$\int_{S} (T_i x_j + T_j x_i) dS = 2 \int_{V} \sigma_{ij} dS$$

The definition of $\overline{\sigma}_{ij}$ is

$$\overline{\sigma}_{ij} = \frac{1}{V} \int_{S} \sigma_{ij} dV$$

which gives our final result that

$$\overline{\sigma}_{ij} = \frac{1}{2V} \int_{S} (T_i x_j + T_j x_i) dS$$